IG-JADE-PKSlib

An Agent-Based Framework for Advanced Web Service Composition and Provisioning

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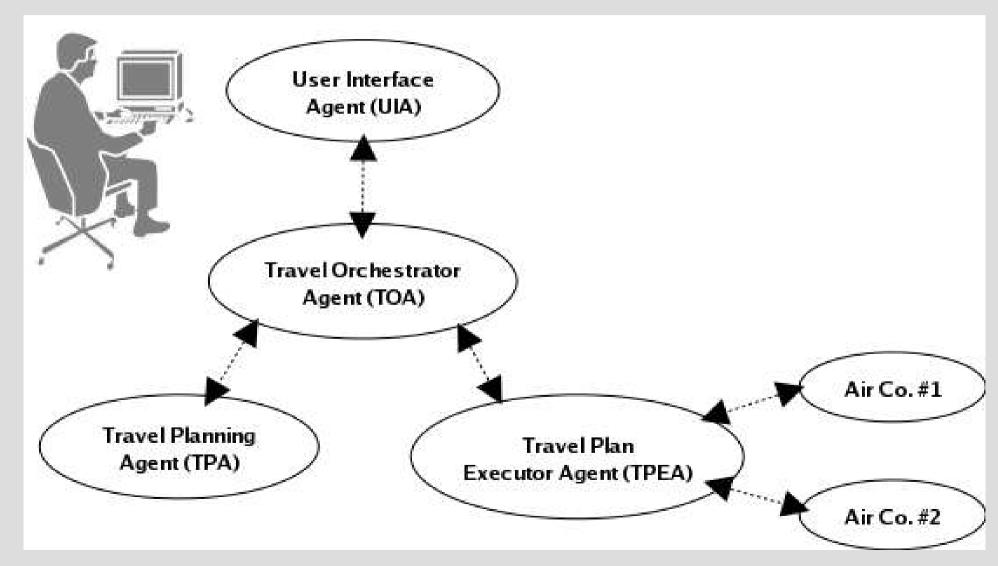
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Motivation

- Next generation Web Services
 - Semantic Web
 - Reasoning / Planning
 - Automation
- Agent-oriented toolkit for advanced MAS / WSC and provisioning
- Previous results (knowledge-based planning)

Air Travel MAS Example

(WSC & Provisioning)



IG-JADE-PKSlib Components

- IndiGolog: high-level model-based programming language based on the situation calculus and good for modeling dynamic domains.
- JADE: open source, Java-based, FIPAcompliant software framework for developing MAS
- **PKS**: efficient knowledge-based planning system, supports incomplete information and sensing actions

IndiGolog (IG) (De Giacomo & Levesque, 1999)

Supports:

- Reasoning about action (e.g., diagnosis)
- Exogenous events handling,
- Sensing,
- Planning / Re-planning,
- Plan execution,
- Execution monitoring

• Limitations:

 mainly intended for designing individual autonomous agents

IG-JADE-PKSlib

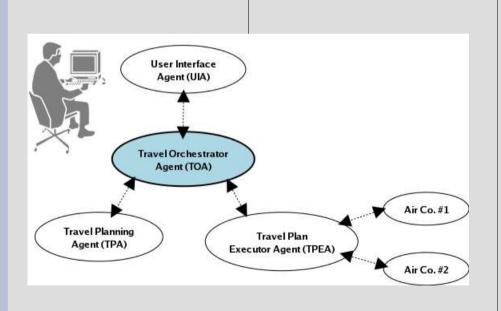
IG Agent Specification

Has two parts:

- Declarative specification of the domain and its dynamics in the situation calculus:
 - Axioms describing the initial situation
 - Action precondition axioms
 - Successor state axioms
 - Sensed fluent axioms
 - Unique names axioms for the primitive actions
 - Some foundational, domain independent axioms
- Procedural description of the agent behaviour in the IG process language
 - Rich programming language, with support for non-determinism, concurrency, interrupts, search, etc.

IG-JADE-PKSlib

IG Travel Orchestrator Agent Example



proc orchControl

```
\pi id, pid, xid.
```

$$?(agent_ID = id),$$

$$?(plan_ID = pid),$$

$$?(\text{exec_ID} = xid),$$

/* Three Concurrent Processes */

handleRequest(*id*) ||

 $handlePlanning(pid) \parallel$

handleExecution(xid)

endProc

Java Agent DEvelopment Framework (JADE) (TILAB/AOT Labs)

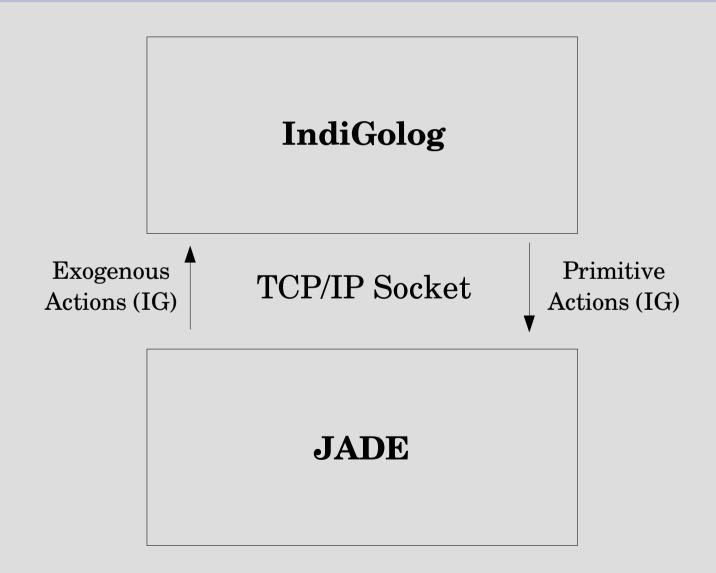
• Supports:

- FIPA-compliant agent architecture
 - Agent Management System
 - Directory Facilitator
 - Agent Communication Channel
- Full implementation of FIPA communication model
 - Agent interaction protocols (AIPs),
 - Agent Communication Language (ACL),
 - SL content language,
 - Some types of ontologies, and
 - Transport protocols

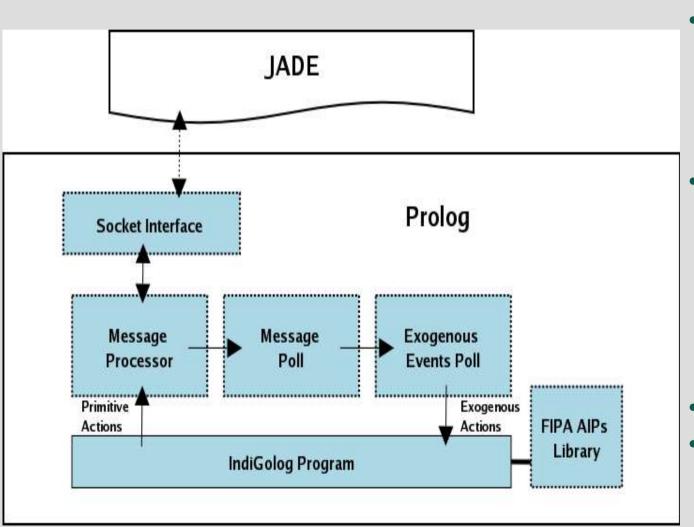
• Limitations:

- Lack of reasoning mechanisms for agents
 - Interface to JESS, but JESS has limitations with respect to reasoning about dynamic domains (e.g., WS)

IG-JADE Interface



IG-JADE Interface (IG Arch.)



Original IG
Limitation: intended
for designing individual
autonomous agents

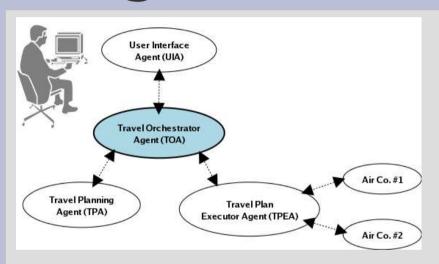
Extended IG Features:

- FIPA ACL (message) handling
- FIPA SL (content) handling
- Support for FIPA AgentInteraction Protocols(AIPs)

Integration to MAS

- Asynchronous communication
 - Proactive + reactive IG agents

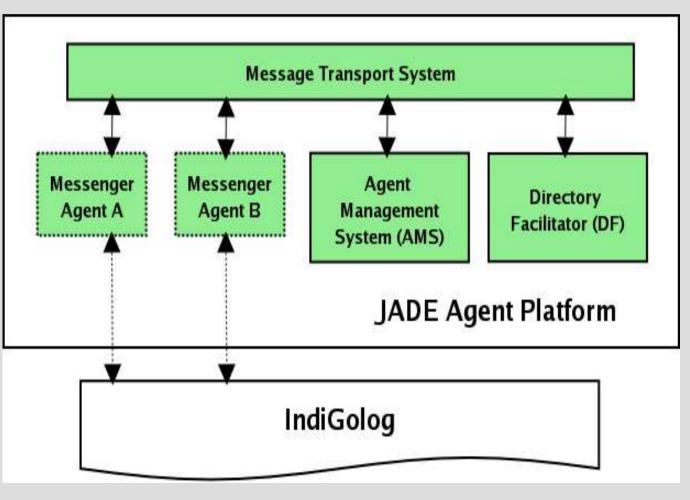
IG Travel Orchestrator Agent Example (Revisited)



```
proc orchControl
    π id, pid, xid .
    ?(agent_ID = id),
    ?(plan_ID = pid),
    ?(exec_ID = xid),
    handleRequest(id) ||
    handlePlanning(pid) ||
    handleExecution(xid)
endProc
```

```
proc handleRequest(id)
 /* FIPA AIP (Request-participant) */
  initRequestParticipantRole(id)
endProc
proc handlePlanning(pid)
  <cid: state_planning(pid, cid) = ready
    /* FIPA AIP (Request-initiator) */
     \rightarrow initRequestInitiatorRole(id)>
     \langle true \rightarrow \mathbf{noOp} \rangle
endProc
```

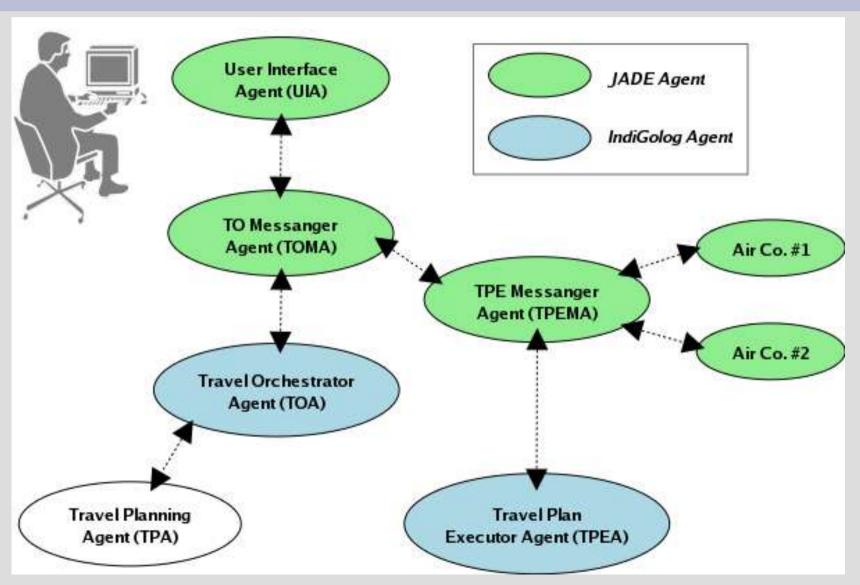
IG-JADE Interface (JADE Arch.)



- Original JADE
 Limitation: lack of reasoning mechanisms for agents (dynamical domains)
- Extended JADE Features:
 - Socket interface to IG
- Messenger is a fullfledged JADE agent
 - ACL handling
 - Translator/mailbox
- Extended capabilities to do reasoning on dynamical domains

Air Travel MAS Example

(Revisited)



Automated Web Service Composition as Planning

• **WSC Problem:** given a set of Web services and some user defined task or goal to be achieved, automatically find a composition of the available services to accomplish the task.

WSC as a Planning Problem:

- Predefined available services as the building blocks of a plan
- Many WS actions involve sensing
- Large search space, incomplete information in the initial state

Planning with Knowledge and Sensing (PKS)

• Supports:

- Planning under conditions of incomplete knowledge
- Sensing actions,
- Parameterized conditional plans,
- Planning at the knowledge level (without considering all the different ways the physical world can be configured),
- Efficient, sound, forward chaining inference algorithm

• Limitations:

- Only limited forms of incomplete knowledge can be represented
- Inference algorithm is efficient but incomplete

WSC in PKS (Martínez & Lespérance, 2004)

- PKS primitive actions correspond to WS
 - Knowledge-producing actions ↔ information gathering WS
 - Physical actions ↔ world-altering WS
- New WS becomes available \rightarrow add new primitive action to domain specification

PKS Spec. Example (Air Travel Domain)

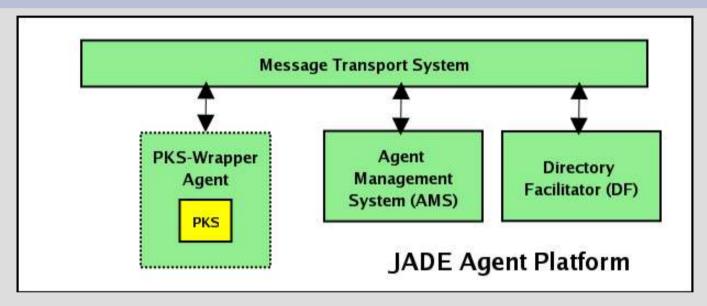
Action	Precondition	Effects
findRFlight(x)	K(airCo(x))	add(Kw, flightExists(x))
	K(indFindRFlight(x))	$add(Kf, \neg indFindRFlight(x))$
	K(desFindRFlight(x))	
bookFlight(x)	K(airCo(x))	add(Kf, bookedFlight(x))
	K(availFlight(x))	del(Kf, availFlight(x))
	K(indBookFlight(x))	$add(Kf, \neg indBookFlight(x))$
	K(desBookFlight(x))	

Domain specific update rules (DSUR)

 $K(airCo(x)) \land \neg Kv(flightNum(x)) \land K(flightExists(x)) \Rightarrow \\ add(Kv, flightNum(x))$

1 explicit parameter: *company*

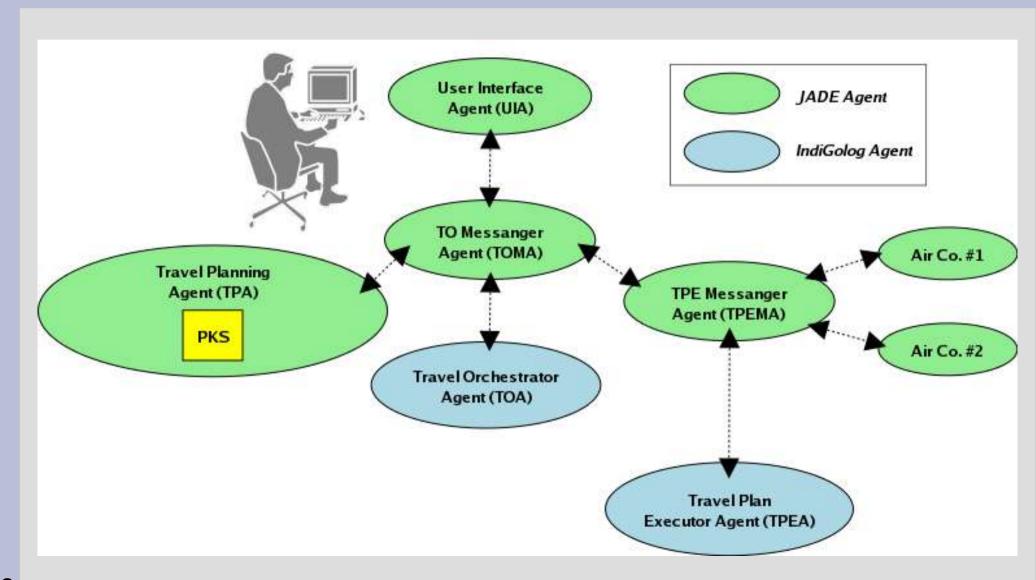
PKS-JADE Interface



- Why PKS-JADE?
 - Both object-oriented: JADE (Java), PKS (C++)
- PKS-WA is a full-fledged JADE agent
 - FIPA AIPs
 - FIPA ACL
 - FIPA SL
 - Ontology support (e.g., pks-ontology)
- Extended knowledge-based planning capabilities

Air Travel MAS Example

(Final / IG-JADE-PKSlib)



Main Contributions

- Extended IndiGolog, added support for:
 - FIPA Agent Interaction Protocols (AIPs)
 - FIPA ACL (message) handling
 - FIPA SL (content) handling
 - Integration to MAS
- Asynchronous communication, proactive + reactive IG agent behaviours
- *IG-JADE-PKSlib*: agent-based infrastructure and toolkit, for developing inter-operable, intelligent MASs (e.g. advanced WS applications)
- Our toolkit provides *comprehensive support* for multiple features, such as: reasoning for dynamical domains, knowledge-based planning (incomplete knowledge, sensing), execution monitoring, AIPs, ontologies, etc.

Open Problems and Future Work

- Translation of OWL, DAML-S, etc. into PKS/IG specifications
- Representation of atomic services
- Customizing domain theory based on problem
 - Automatic generation (desc. goal + user pref.)
- *IG-PKS* interface (i.e., IG built-in KB planning)
 - IG passes planning calls to PKS (efficient)
 - Prolog-based reimplementation of PKS (more flexible, but less efficient)
- Experiments + case studies to validate performance and scalability of integrated framework [Martínez & Lespérance, 2004]
- Plan execution and contingency recovery

Thank You!